

TAN CANG OFFSHORE SERVICES

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MEDIUM DUTY WORK CLASS ROV

PERRY XLX-C08

(Year built 2019)

DEVELOPED FOR

- Heavy Construction Support
- Platform, Pipeline & Cable Inspection
- Platform, Pipeline & Cable Maintenance
- Subsea Intervention
- ♦ Submarine / Maritime Rescue

- Drilling Support & Intervention Operations
- ♦ Pre/Post surveys
- Route, Site & UXO Survey
- ♦ Installation Support
- ♦ Pipeline & Cable Lay Clearance Inspection

ROV INTRODUCTION



The Perry® XLX-C is a compact heavy-duty work-class hydraulic ROV, complementing the Perry® XLXEvo 150-250 series of larger heavy-duty work-class ROVs.

The Perry® XLX-C ROV system represents the latest evolution in the highly successful Perry® XL series.

The XLX-C features significantly enhanced performance across the full range of demanding intervention and survey tasks without compromise to the outstanding reliability for which the XL series of vehicles is renowned throughout the world.

@ 230 bar (60 Hz)

Horizontal

Vertical

REMOTELY OPERATED VEHICLE (ROV)

REPORTED OF ENAITED VEHICLE (ROV)				
Class	Medium Duty Work Class	Dimensions 2800 mm (L) - State		atoil config 2500 mm
Depth Rating	3000 msw (option for 4000 msw – size, weight and payload same as 3000 m)		1700 mm (W)	
			1900 mm (H) - Ov	er bumper 2000 mm
Power	150 hp	Bollard Pull	Forward	800 kgf
Through Frame Lift	3000 kg	(with 60Hz supply)Lateral		800 kgf
Control System	ICE™ Real Time Control System		Vertical (lift/dive)	700 kgf / 550 kgf
	with GHz Optical Link, Ethernet Telemetry and Graphical Diagnostics Heading, Depth, Altitude, Park & Dynamic Positioning	Surface Speed	Forward	3.5 knots
Control Modes		(with 60Hz supply	v)Lateral	2.8 knots
			Vertical	3.0 knots
Payload Capacity	200 kg	Load Capacity	Forward Lower	250 kg at 250 mm
Weight In Air	4200 kg		Forward Upper	250 kg at 500 mm
Auto Functions	(Heading, Depth, Altitude, Park,		Aft	300 kg at 500 mm
	Dynamic Position)		Side	150 kg at 250 mm
Heading Control	± 1.0°	Main Hydraulic	Type 238 L/min	

Thrusters

Depth Control

Altitude Control

Pitch & Roll Control ± 5.0°

± 150 mm

± 150 mm

4 x 300 mm

4 x 300 mm



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STANDARD EQUIPMENT

Cameras Up to 8 Cameras (EMCCD/SIT

equiv./near SIT low light B/W, colour, zoom/fixed, manip cam, light

ring, HD (3 max), etc.)

Lights Up to 6 individually dimmable lights

Pan & Tilts Hydraulic SA-A-5735-MAS (2 fwd.)

Depth Sensor $\pm 0.01\%$

Main Valve Pack Bidirectional 10-Station (12 L/min,

each proportional flow, overall

pressure.

Manipulators 7 Function Manip. Schilling Titan 4

5 Function Grab. Schilling Rigmaster

♦ Obstacle Avoidance Sonar or multibeam acoustic camera.

♦ Heading, Pitch and Roll Sensor (FOG).

◆ RF Beacon, Emergency Xenon Flasher.

SYSTEM OPTIONS

◆ Auxiliary Hydraulic System (120 L/min @ 207 bar, 60 Hz).

♦ North seeking Gyro / INS.

◆ Transponders / responders.

Auxiliary Valve Pack Bidirectional 10-Station (12 L/min,

each proportional flow, overall

pressure)

High Flow VP Bidirectional 2 or 4-Station (25, 75

or 140 L/min, each proportional pressure & flow, integrated torque

tool control)

Water Filter Cardev (Main and Auxiliary)

Survey JB RS232/RS485 & power channels,

camera channels, light channels, space for high bandwidth

interfaces

High speed data Gigabit Ethernet/PECL Interfaces

for Multibeam sonars, Profilers, etc.

Workskids (not supplied)

◆ Survey & Bathymetric suites.

Jetting Module.

◆ Tool Interface Module.

◆ Suction Pile System.

♦ Variable Ballast Module.

VIDEO - SERIAL - POWER & FIBRE OPTIC

- ◆ Standard Definition Composite Video Channels (8)
- ◆ Individually dimmable light channels (6)
- ♦ Dedicated serial and power channels for Controls, Valve Packs, Gyro, Depth, Altimeter/DVL, OA Sonar, Manip & Resp. Trigger
- ◆ Spare RS232/RS485 Serial Channels (7 typ)
- ◆ Singlemode Fibres: to Vehicle (2), to TMS (1)
- ◆ Spare CWDM Channels (12)
- ◆ Current Monitoring & Protection on each Power Channel

CONTROL SYSTEM

- ◆ Utilizes the revolutionary ICE™ Integrated Control Engine
- ◆ Fully redundant Windows® based HMI Computers.
- Dedicated real-time controllers.
- ◆ Intuitive Graphic User Interface (GUI).
- Advanced interactive graphical diagnostics.
- ♦ User configurable GUI.
- ♦ Video Wall (9" x 24" HD LCD Monitors).
- Ergonomic pilot/co-pilot control consoles combining touch screen and physical switch control interfaces.

TYPICAL SURFACE POWER DISTRIBUTION

- ♦ 225 kVA Transformer for Vehicle Hydraulics.
- ♦ 8.5 kVA Transformer for Vehicle Electronics.
- ♦ 15 kVA Transformer for TMS-HPU.
- ♦ 1.5 kVA Transformer for TMS Electronics.
- ◆ 230 kVA steady state load.
- Ground fault detection circuits.
- Deck cable interface.
- ♦ CB, O/L and current/voltage sensors/meters.

TETHER MANAGEMENT SYSTEM (TMS)

Model Top hat

Tether length Type 4 up to 440m of Ø35mm Tether

Type 4 up to 750m of Ø27mm Tether

Type 5 up to 750m of Ø35mm Tether

Type 5 up to 1150m of Ø27mm Tether

Dimensions 1971 mm (L) x 2021 mm (W)

2204 mm (H)

Weight 3130 kg



Main Umbilical

Dimensions

Weight

Umbilical Length

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Model

Type

Weight

Type

Dimensions

Weight

Dimensions

LAUNCH & RECOVERY SYSTEM (LARS)

A-Frame **Dimensions** 8017 mm (L) x 3638 mm (W) x

3201 mm (H)

DECK PACK

STORE VAN SPECIFICATION

1372 mm (L) x 1028 mm (W)

A60 Container DNV Compliant Std

6000 mm (L) x 2500 mm (W)

Deck Pack Control

1145 mm (H)

20ft Container

2900 mm (H)

12000 kg

1021 kg

Weight 27216 kg

HYDRAULIC POWER UNIT (HPU)

25550 kg

4082 mm (H)

WINCH

3240 mm (L) x 3783 mm (W)

Armored

2300 mts

Type Hydraulic Power Unit

Dimensions 2362 mm (L) x 1439 mm (W)

2235 mm (H)

Weight 3700 kg

CONTROL VAN SPECIFICATION

Type 20ft Container

A60 Control Cabin DNV Compliant Stc

Dimensions 6000 mm (L) x 2500 mm (W)

2900 mm (H)

Weight 12000 kg Gross

Incoming Power 400 VAC & 3Ø50Hz & 200 KW

◆ Advanced Console or Integrated Control Chairs.

♦ Large Video Wall (12" x 24" HD LCD Monitors).

◆ Sonar Computer, Keyboard & Topside Processor Unit.

♦ 4 channel DVR unit.

♦ Wired/wireless Deck Communications.

◆ 3D Training Simulator with General & User Spec. Scenarios

ROV WORKSHOP

Addre No. 69, 30/4 Street, Thang Nhat Ward

Vung Tau City, Ba Ria Vung Tau Province, VN.

+84 2543 812 968 Tel

Fax +84 2543 812 121

OFFICE

Address 02nd floor, 11 Nguyen Cong Tru Street

District 1, Ho Chi Minh City, Vietnam.

Tel +84 28 3914 3982 +84 28 3821 6446 Fax

http://www.saigonnewport.com.vn Web